

May 14, 2020

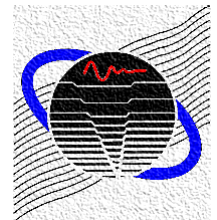
# Measurements using Smart Phone Apps and the PU Probe

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Vibro-Acoustics Consortium Web Meeting  
University of Kentucky

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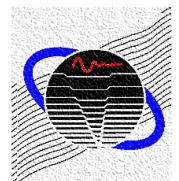
**Vibro-Acoustics Consortium**



# Overview

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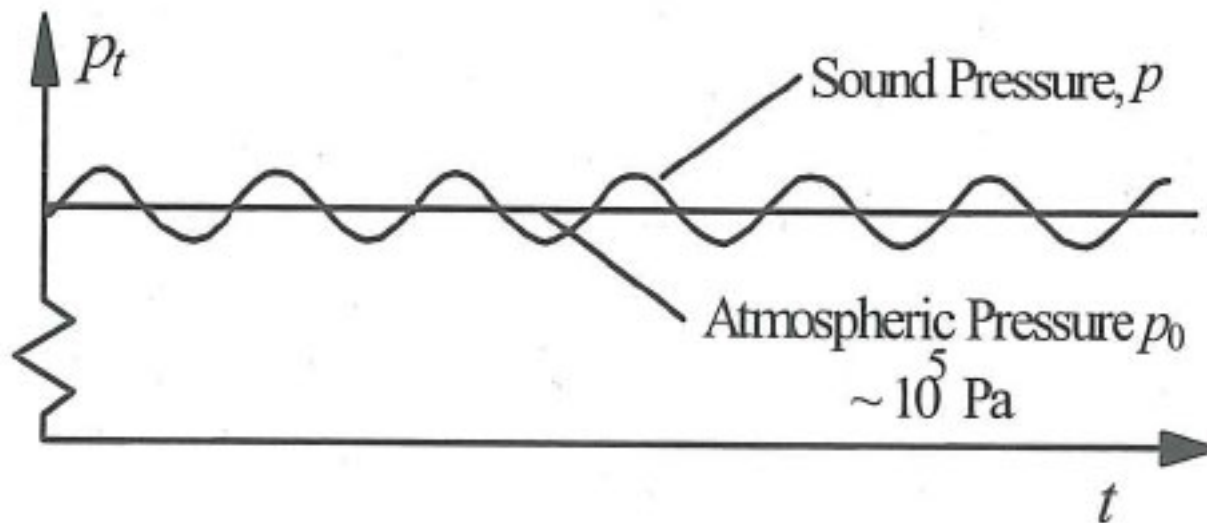
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- PU Probe Engine Application
- PU Probe UAV Application
- PU Probe Radiation Efficiency
- Future Directions



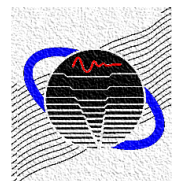
# Sound and Vibration Fields

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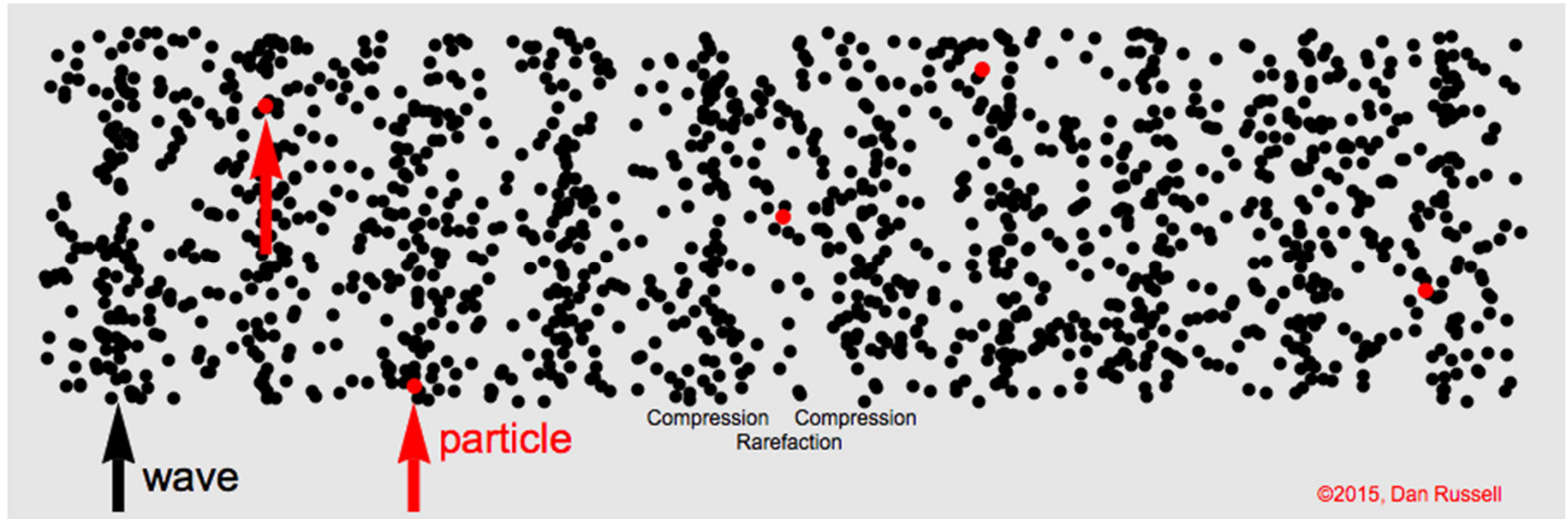
An acoustic field implies a small disturbance. Sound pressure disturbances are only on the order of 1 Pa for 94 dB.



Wallin et al., 2011

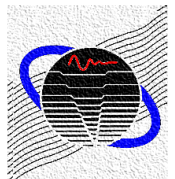


# Particle Motion



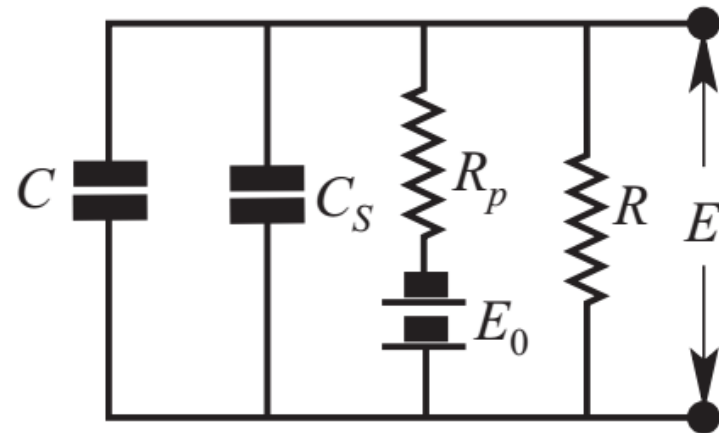
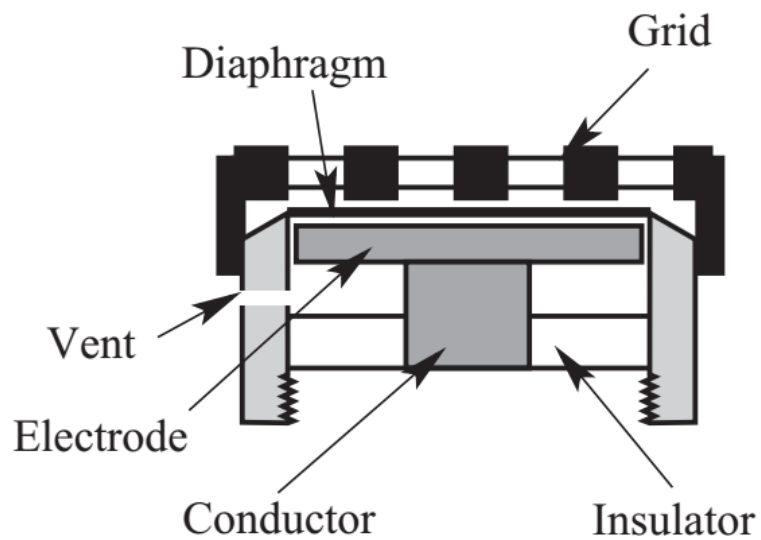
- Particles oscillate (but no net flow)
- Waves move much faster than particles

<https://www.acs.psu.edu/drussell/demos.html>

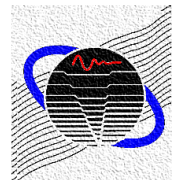


# Condenser Microphones

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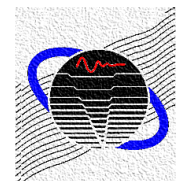
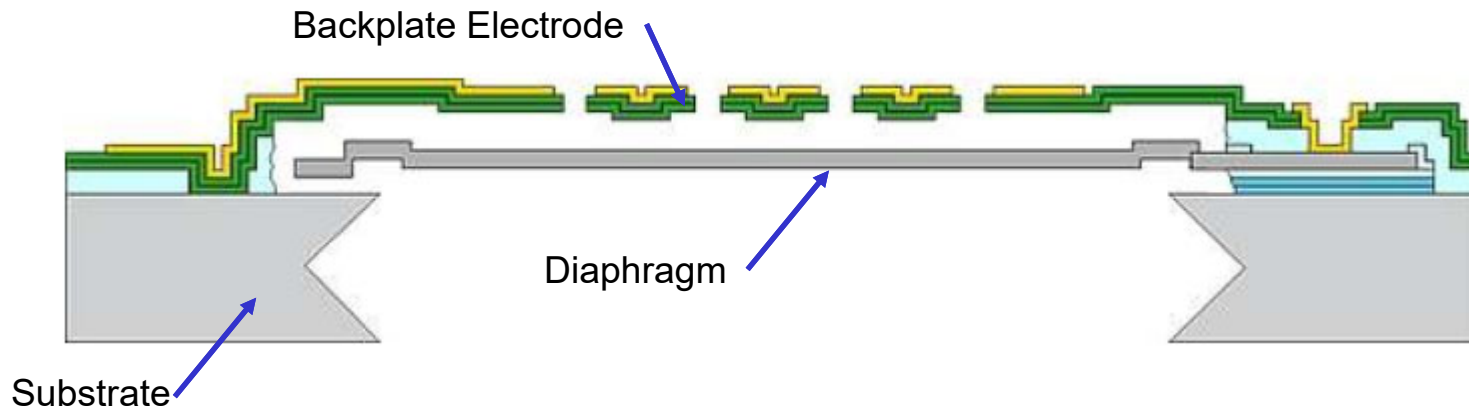
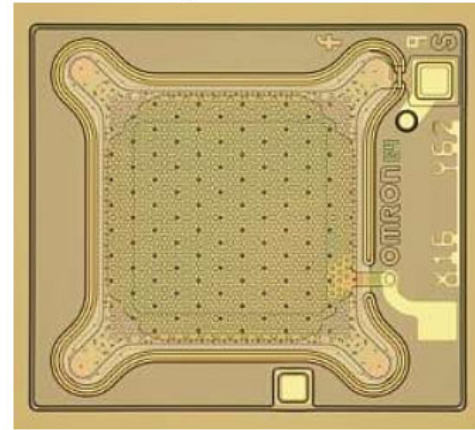


Bies, Hansen and Howard, 2018



# MEMS Microphones

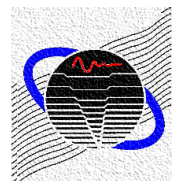
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# Smartphone Types

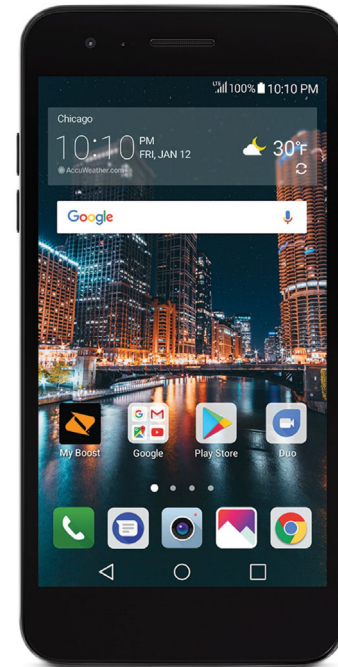
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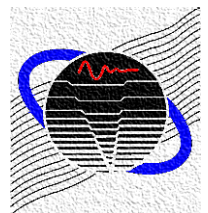
iPhone 6 Plus



iPhone 7 Plus



LG Tribute Dynasty

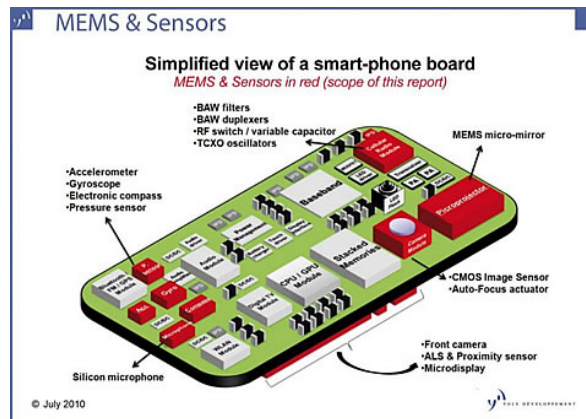




# Microphones



PCB 378B11  
Siemens DAQ

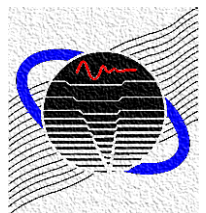


Internal Microphone

<https://www.engineering.com/ElectronicsDesign/ElectronicsDesignArticles/ArticleID/6124/How-MEMS-Enable-Smartphone-Features.aspx>



Mic-W  
BSWA



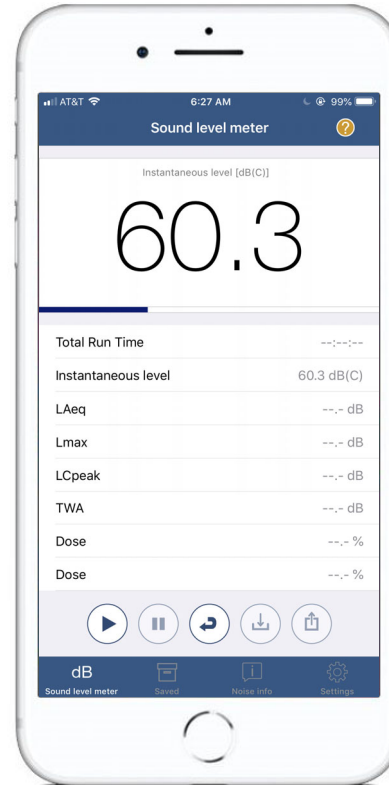
# Smartphone Apps Used



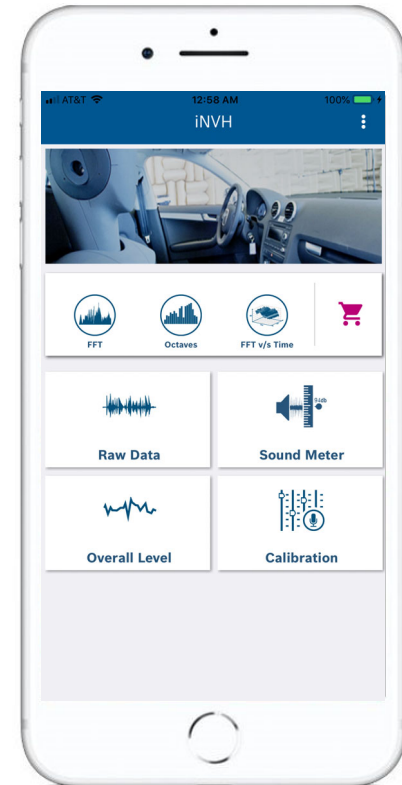
Sound Meter X  
Faber Acoustical



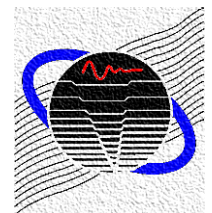
Signal Scope X  
Faber Acoustical



NIOSH SLM



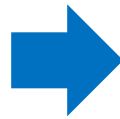
iNVH  
Bosch



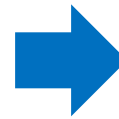
# Microphone Calibration



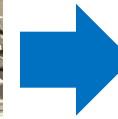
Calibrate the PCB microphone



Mount the sensors together



Measure in "free field"

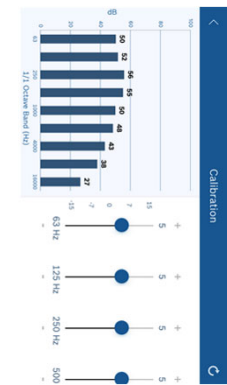
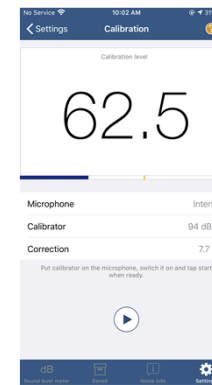
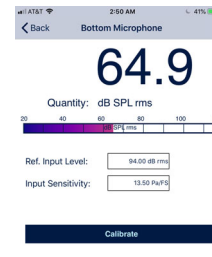
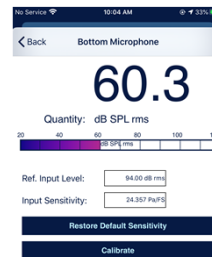
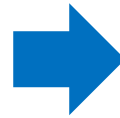


Sources Control

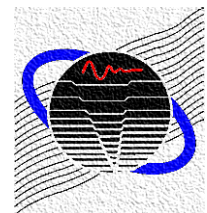
	Source	On/Off	Signal Type	Level (V)	More
1	Output1	<input checked="" type="checkbox"/>	Random	1.0000	More
2	Output2	<input type="checkbox"/>	Sine	0.0000	More

Start Source      Stop Source

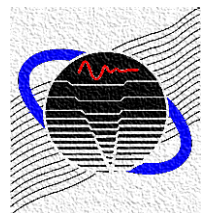
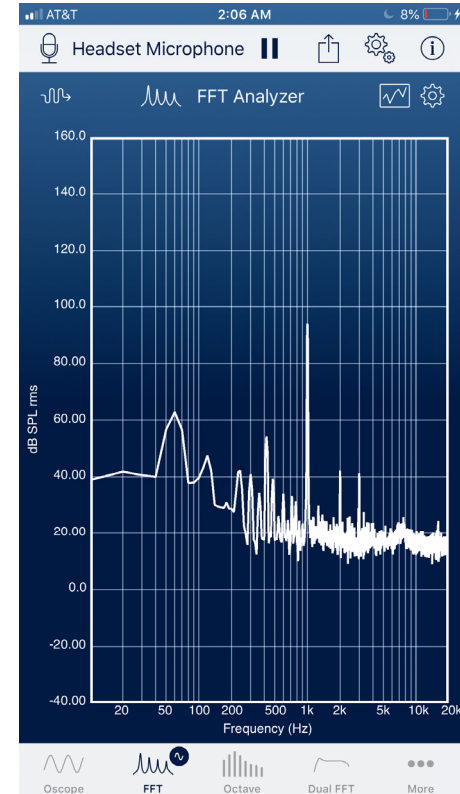
Generate a 94 dB noise (measured by PCB microphone)



Calibrate the Apps



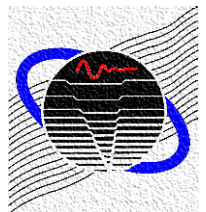
# Microphone Calibration



# Overview

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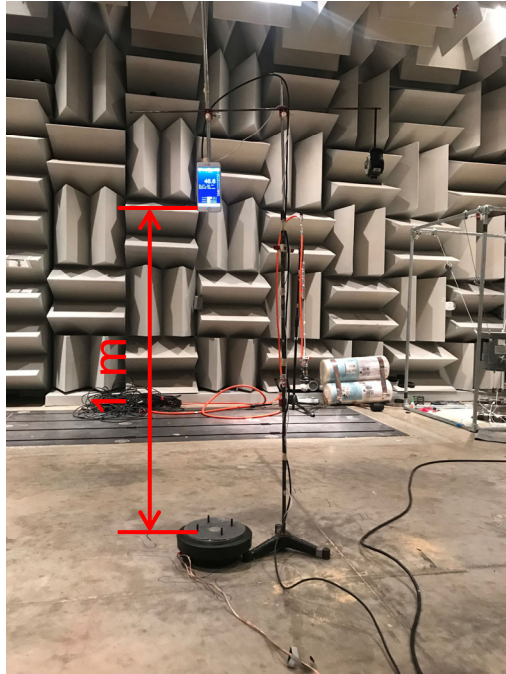
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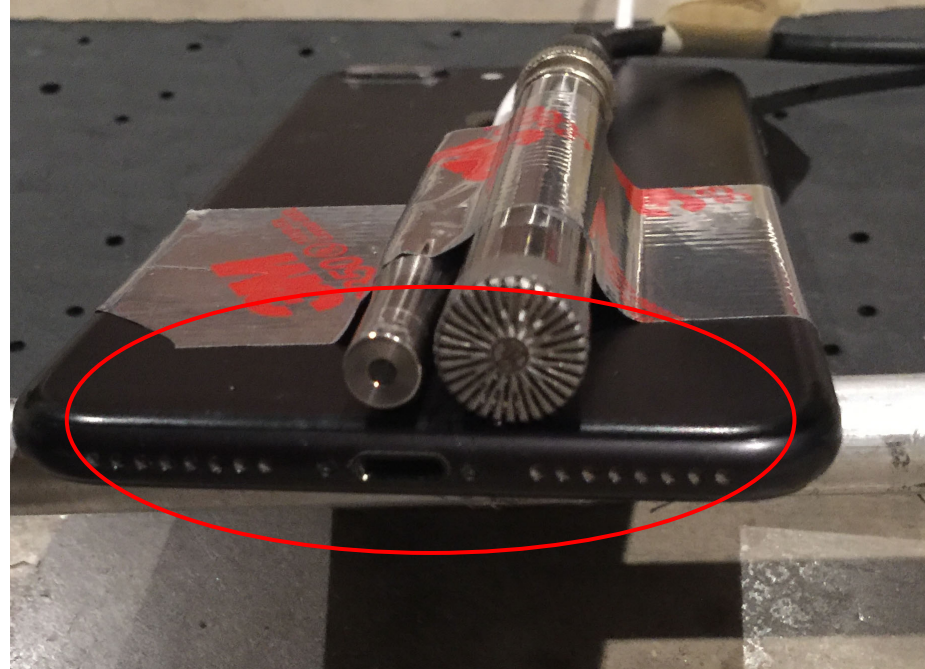


# Test Setup

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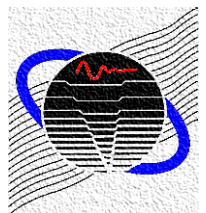


Free space measurement



Smartphone and microphones

The Smart phone, Mic-W and PCB microphone are mounted directly above (1 m) the loudspeaker.

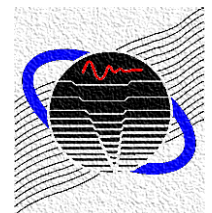


# iPhone 6 Plus with Internal Microphone

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White noise source with internal microphones uncalibrated.

Sound Pressure Level (dB)					
Sound Meter	PCB	NIOSH	PCB	iNVH	PCB
60.0	62.0	60.0	58.7	60.0	61.5
65.0	66.8	65.0	63.2	65.0	66.5
70.0	71.7	70.0	68.1	70.0	72.0
75.0	76.6	75.0	73.2	75.0	76.2
80.0	81.4	80.0	78.1	80.0	81.3
85.0	86.5	85.0	83.2	85.0	86.2
90.0	91.5	90.0	88.2	90.0	91.3
95.0	96.5	95.0	93.2	95.0	96.3
100.0	102.3	100.0	98.5	100.0	101.8

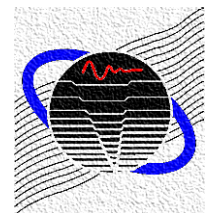


# iPhone 6 Plus with Internal Microphone

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White noise source with internal microphones calibrated.

Sound Pressure Level (dB)					
Sound Meter	PCB	NIOSH	PCB	iNVH	PCB
61.5	62.0	58.2	58.7	61.3	61.5
66.5	66.8	63.2	63.2	66.3	66.5
71.5	71.7	68.2	68.1	71.3	72.0
76.5	76.6	73.2	73.2	76.3	76.2
81.5	81.4	78.2	78.1	81.3	81.3
86.5	86.5	83.2	83.2	86.3	86.2
91.5	91.5	88.2	88.2	91.3	91.3
96.5	96.5	93.2	93.2	96.3	96.3
101.5	102.3	98.2	98.5	101.3	101.8

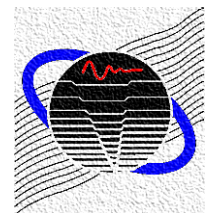




# iPhone 6 Plus with Mic-W

White noise source with Mic-W calibrated with white noise.

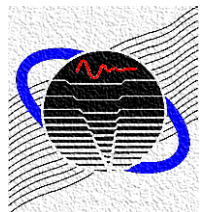
Sound Pressure Level (dB)					
Sound Meter	PCB SCADAS	NIOSH	PCB SCADAS	iNVH	PCB SCADAS
60.7	60.2	60.5	59.9	63.0	60.2
65.4	65.2	65.3	65.2	66.0	64.8
70.2	70.1	70.0	70.0	70.0	69.5
75.0	75.1	75.0	75.1	75.0	74.6
80.0	80.0	80.0	80.0	80.0	79.4
85.0	85.1	85.0	85.0	85.0	84.4
90.0	90.2	90.0	90.0	90.0	89.6
95.0	95.2	95.0	95.0	95.0	94.6
100.0	100.1	100.0	99.9	100.0	99.5



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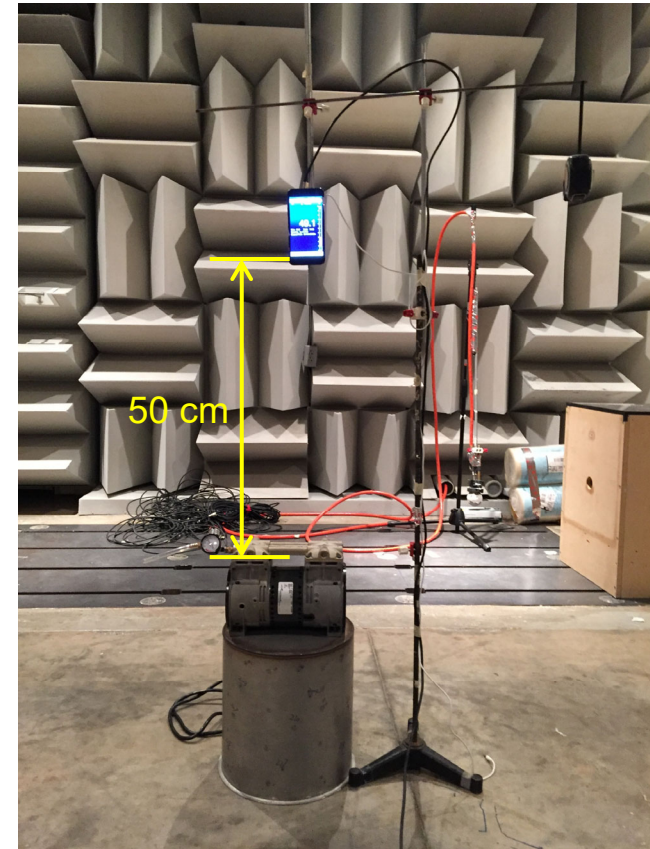
# Compressor Noise SPL Comparison

The smartphone, Mic-W and PCB microphone are mounted directly above the compressor.

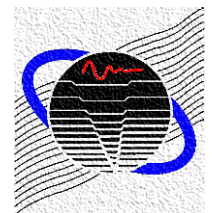
Apps are calibrated using 94 dB @ 1 kHz.

SPL is in dB.

Device	Sound Meter	NIOSH	iNVH	PCB
Internal Microphone (iPhone 7 Plus)	85.2	83.6	85.2	86.7
Mic-W (iPhone 6 Plus)	85.1	83.4	84.8	86.7



Free space



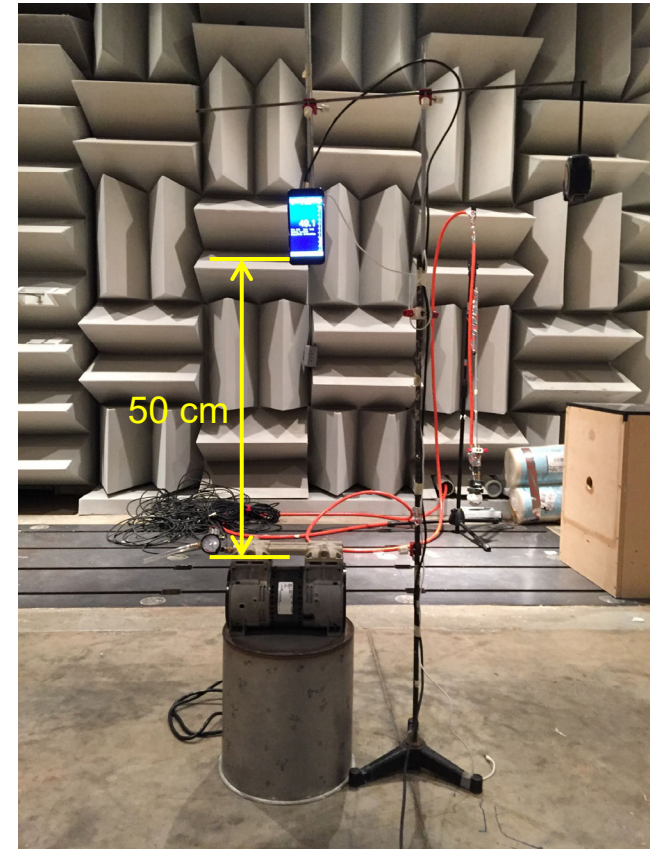
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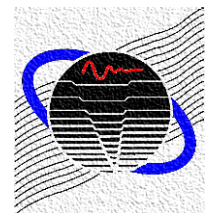
Apps are calibrated using 94 dB @ 1 kHz.

SPL in dBA.

Device	Sound Meter	NIOSH	iNVH	PCB
Internal Microphone (iPhone 7 Plus)	82.6	82.8	83.0	83.8
Mic-W (iPhone 6 Plus)	82.4	82.6	82.0	83.8



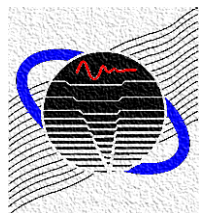
Free space



# Impedance Tube SPL Comparison

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- The Smartphone, Mic-W and PCB microphone are mounted adjacent to one another at the end of an impedance tube.

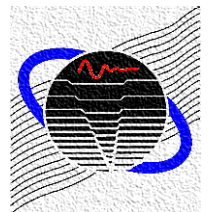


# Impedance Tube SPL Comparison

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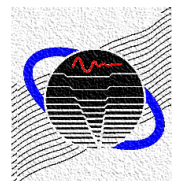
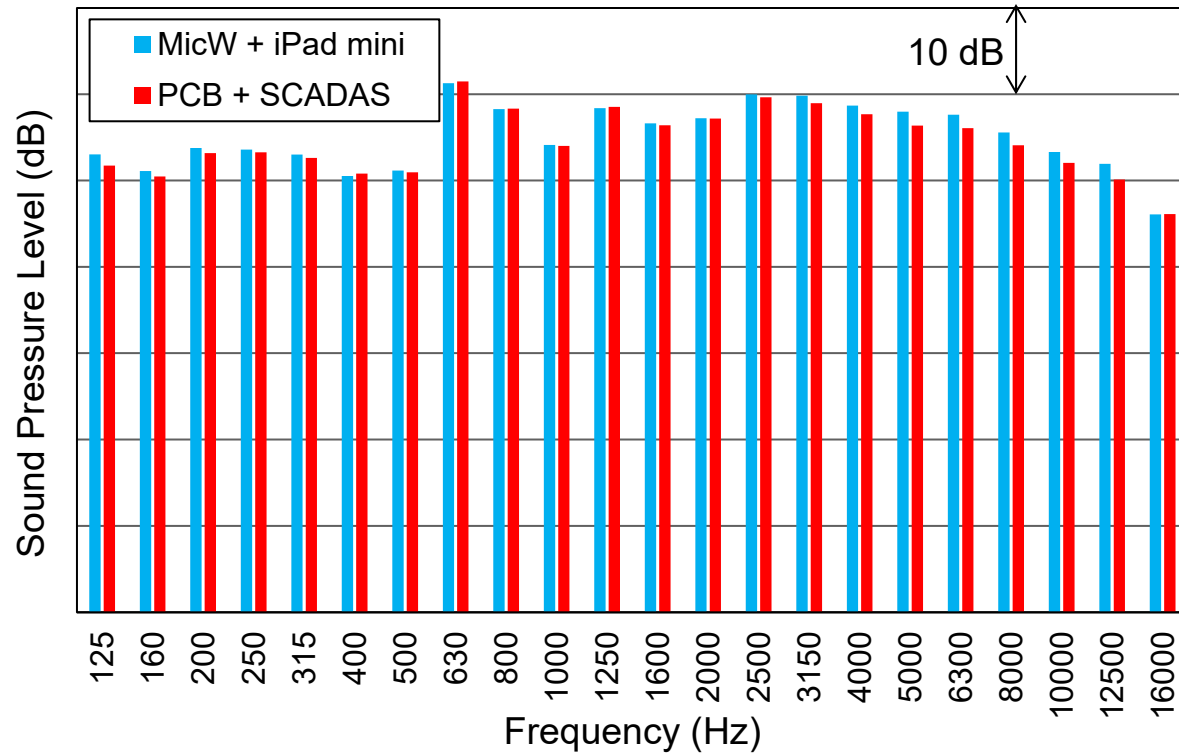
White Noise Source

PCB Mic Siemens DAQ Reference	Mic-W Signal Scope	LG Internal Mic Sound Meter
84.5	85	81
89.7	90	83
94.5	95	85
99.2	100	86
104.5	105	87
109.8	110	88



# Motorcycle Engine SPL Comparison

Microphones are placed 1 m far away from Harley Davidson Engine (idle running).



# Summary

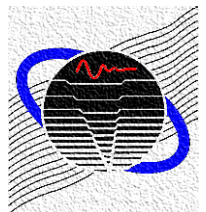
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## Pros

- Portable
- Easy to use
- Good accuracy below 10 kHz
- Inexpensive

## Cons

- Issues at low frequency and low sound pressure levels

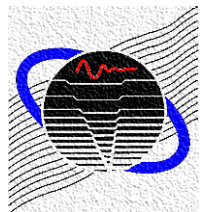




# Overview

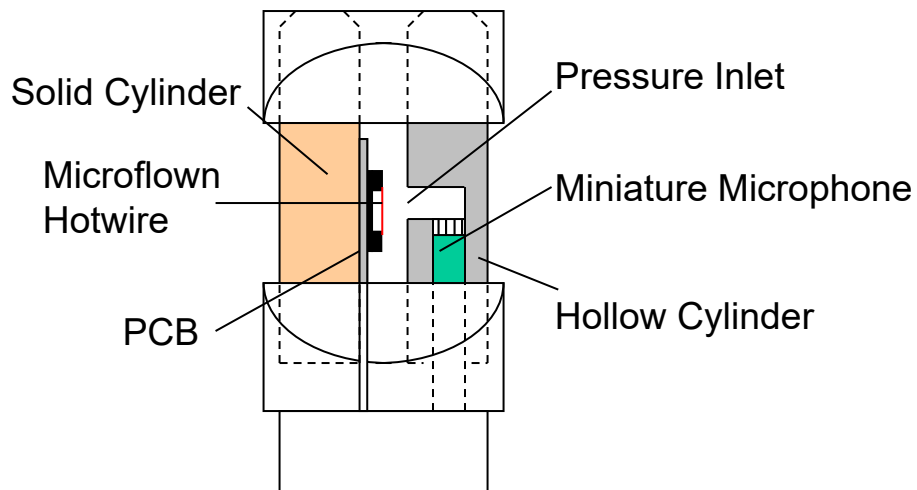
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# Microflow PU Probe

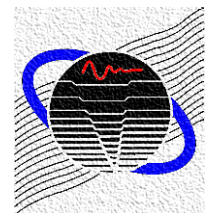
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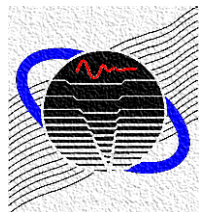
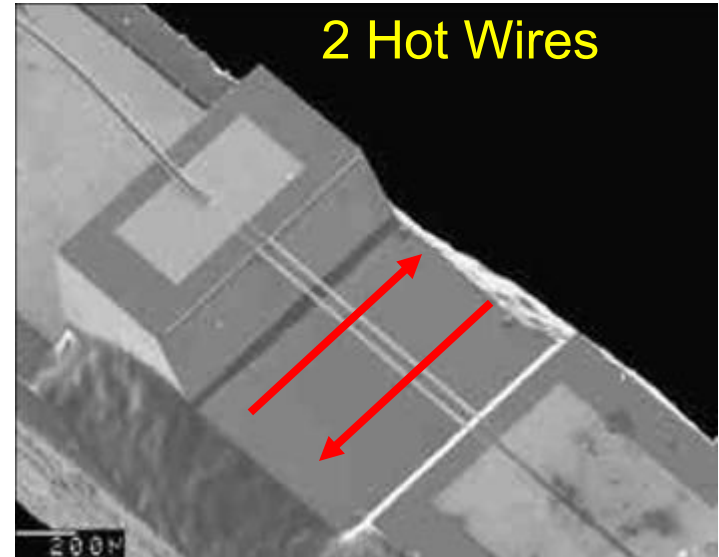
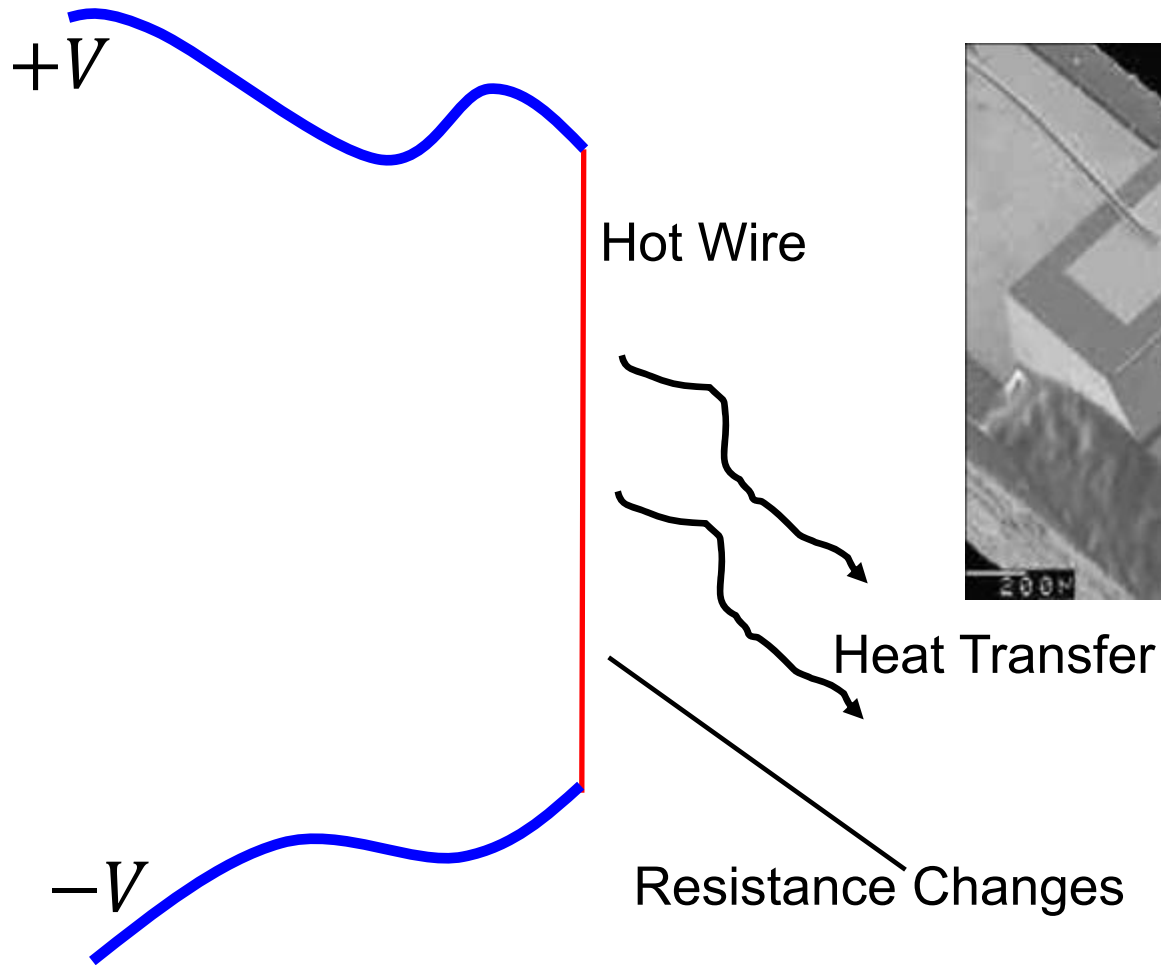
P-U Probe



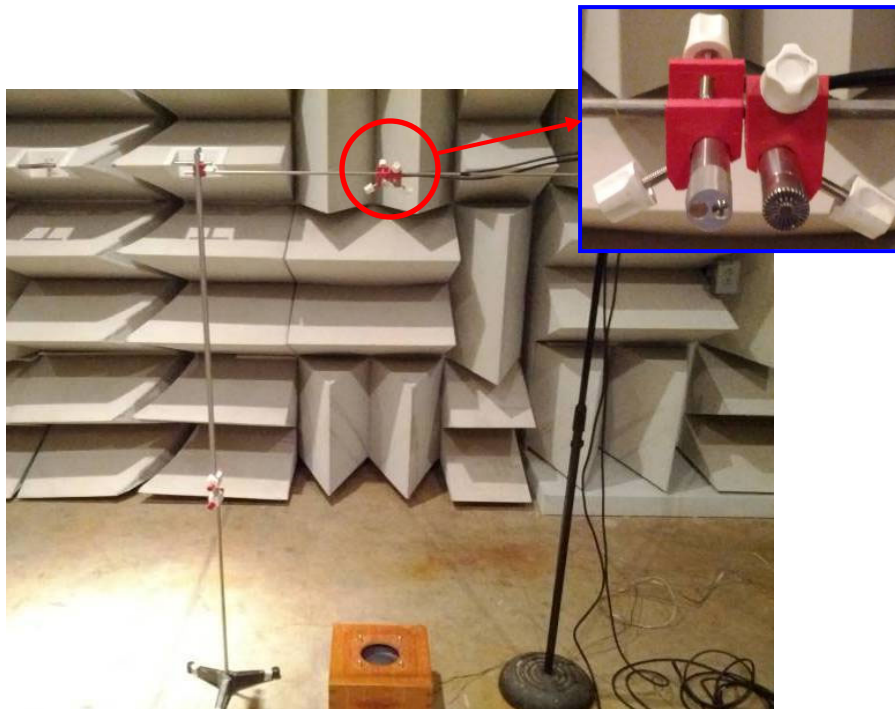
P-U Probe with Wind Shield



# Microflow PU Probe

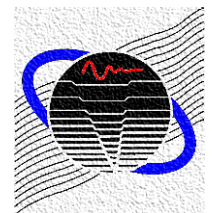


# Microflown PU Probe Calibration

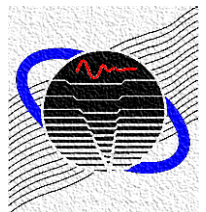
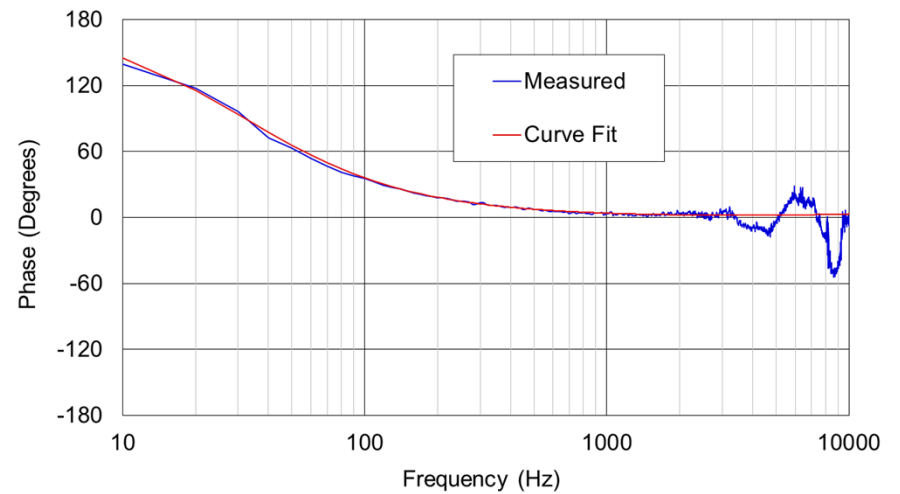
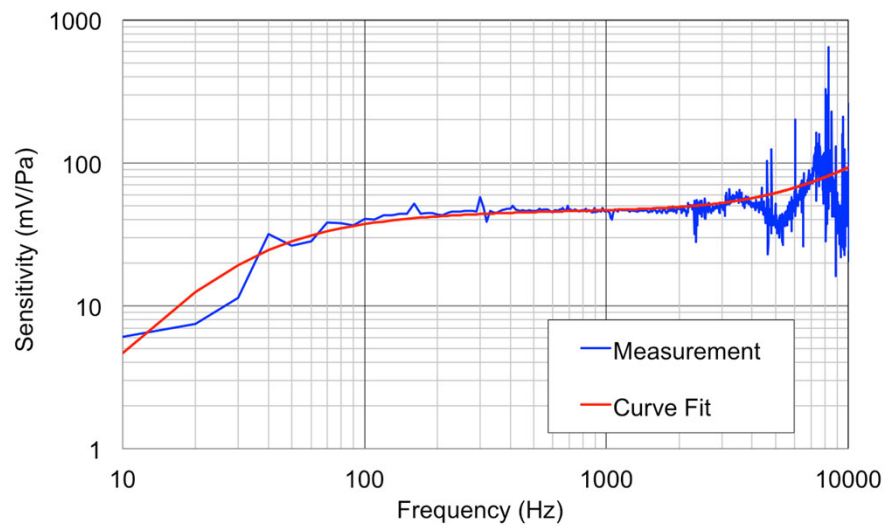


Impedance: 
$$Z = \rho c \frac{ikr}{1 + ikr}$$

1. Use microphone to calibrate pressure sensor.
2. Use  $|Z|$  to calibrate the sensitivity of the velocity sensor.
3. Use  $\angle Z$  to calibrate the phase of the velocity sensor.



# Sound Pressure Sensitivity and Phase



# Microphone Calibration

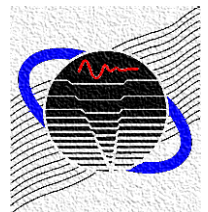
Parameters Pressure	
$S_p$	47
$f_{c1p}$	32
$f_{c2p}$	20
$f_{c3p}$	5848
$C_{1p}$	28
$C_{2p}$	37
$C_{3p}$	200000

## Sensitivity

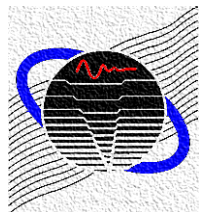
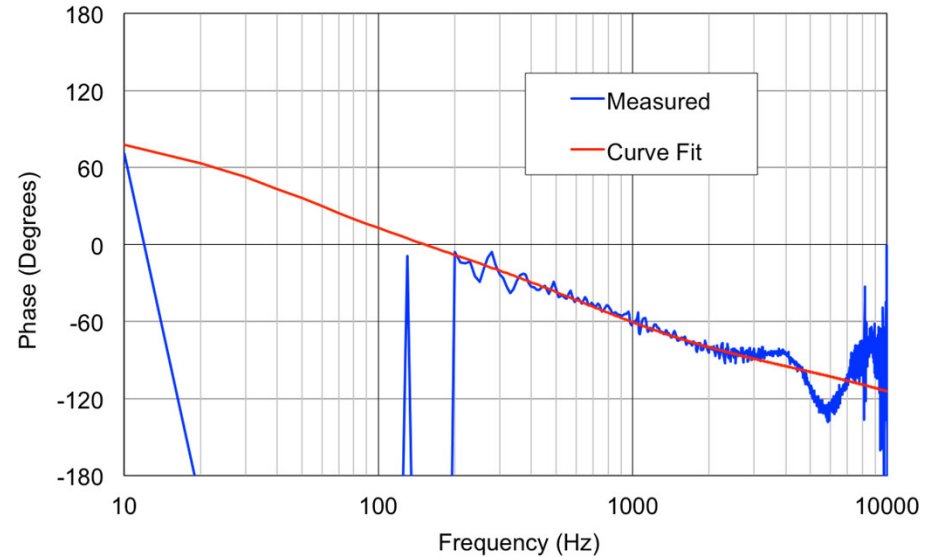
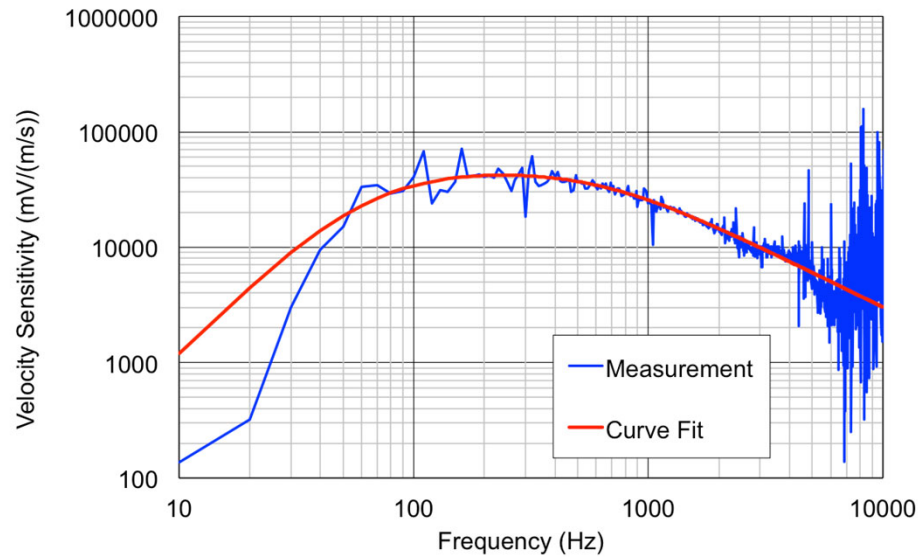
$$S_p \left[ \frac{\text{mV}}{\text{Pa}} \right] = S_p @ 1 \text{ kHz} \frac{\sqrt{1 + \left( \frac{f}{f_{c3p}} \right)^2}}{\sqrt{1 + \left( \frac{f_{c1p}}{f} \right)^2} \sqrt{1 + \left( \frac{f_{c2p}}{f} \right)^2}}$$

## Phase

$$\varphi_p [\text{deg}] = \arctan \left( \frac{C_{1p}}{f} \right) + \arctan \left( \frac{C_{2p}}{f} \right) + \arctan \left( \frac{f}{C_{3p}} \right)$$



# Particle Velocity Sensitivity and Phase



# Particle Velocity Calibration

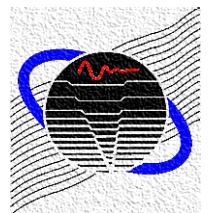
Parameters Velocity	
$S_u$	48000
$f_{c1u}$	63
$f_{c2u}$	633
$f_{c3u}$	97580
$f_{c4u}$	62
$C_{1u}$	1
$C_{2u}$	699
$C_{3u}$	24000
$C_{4u}$	50

## Sensitivity

$$S_u \left[ \frac{\text{mV}}{\text{m/s}} \right] = \frac{S_u @ 250 \text{ Hz}}{\sqrt{1 + \left( \frac{f_{c1u}}{f} \right)^2} \sqrt{1 + \left( \frac{f}{f_{c2u}} \right)^2} \sqrt{1 + \left( \frac{f}{f_{c3u}} \right)^2} \sqrt{1 + \left( \frac{f_{c4u}}{f} \right)^2}}$$

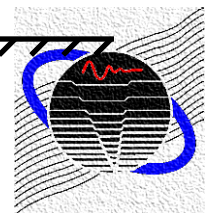
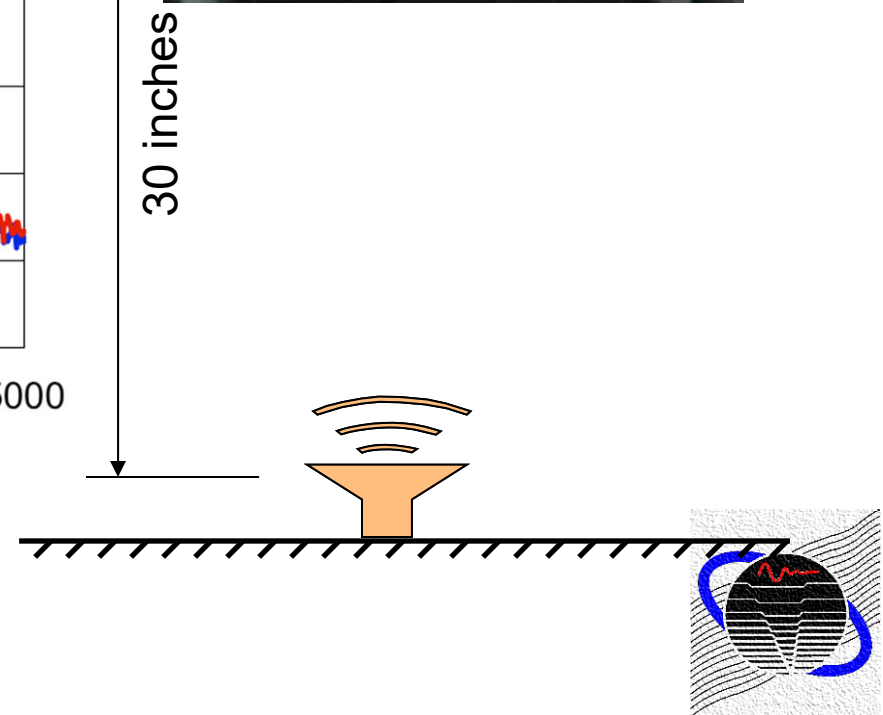
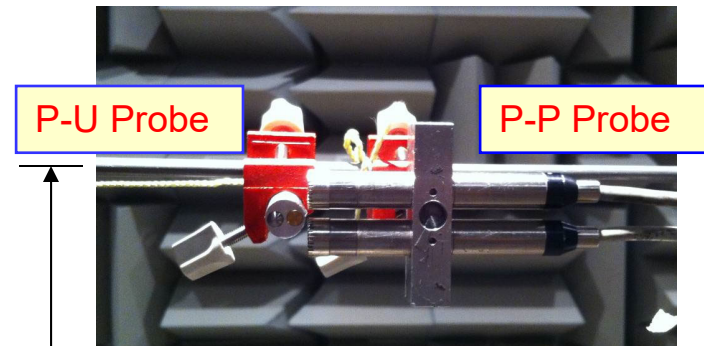
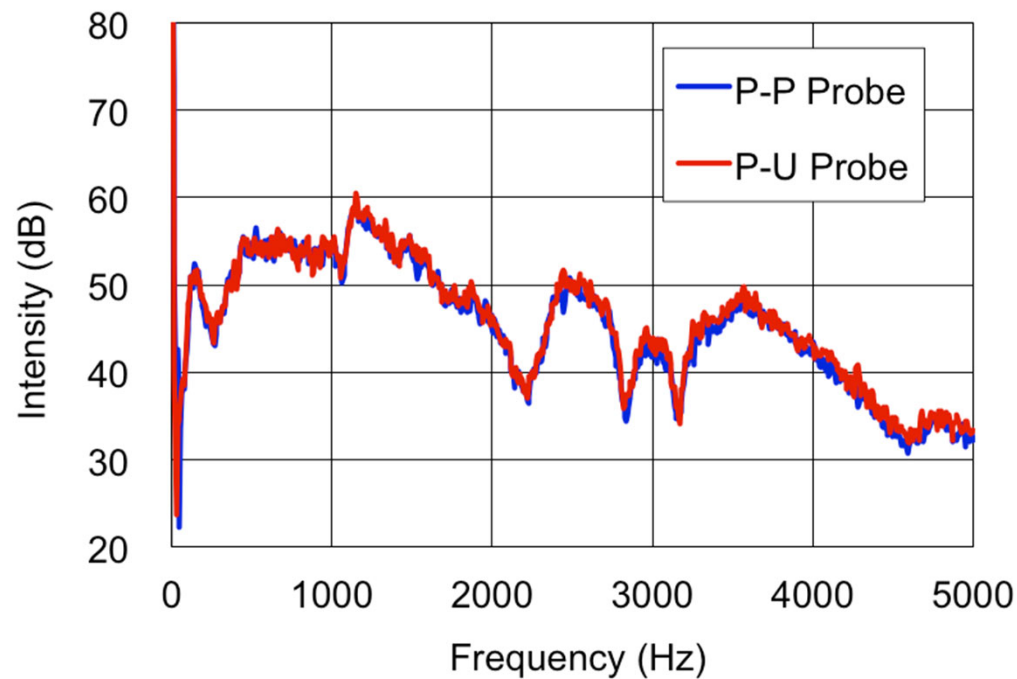
## Phase

$$\varphi_u [\text{deg}] = \arctan \left( \frac{C_{1u}}{f} \right) - \arctan \left( \frac{f}{C_{2u}} \right) - \arctan \left( \frac{f}{C_{3u}} \right) + \arctan \left( \frac{C_{4u}}{f} \right)$$





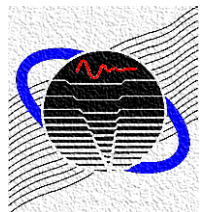
# Sound Intensity Comparison



# Overview

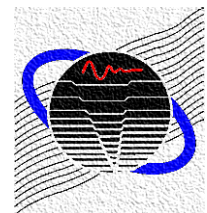
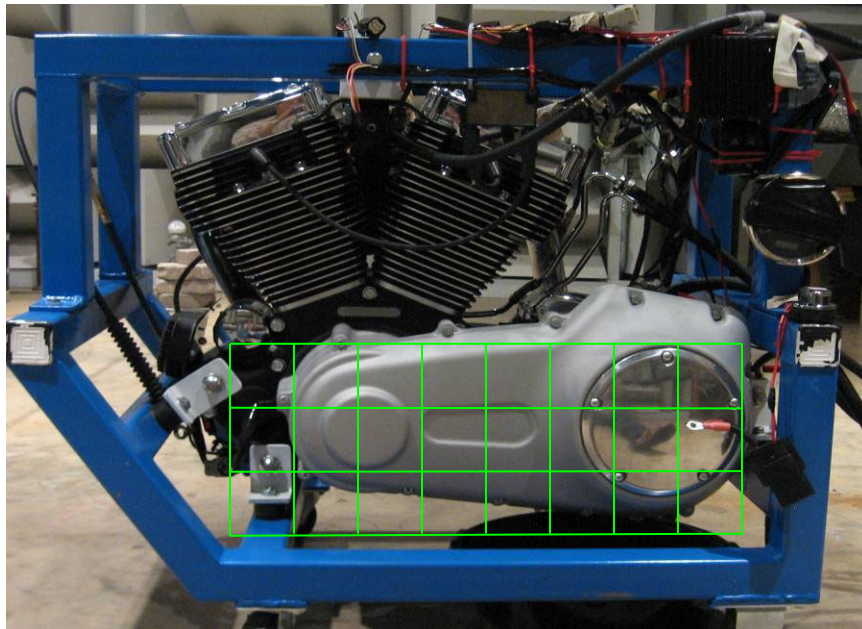
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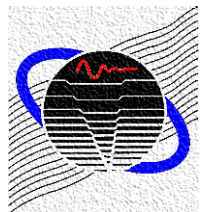
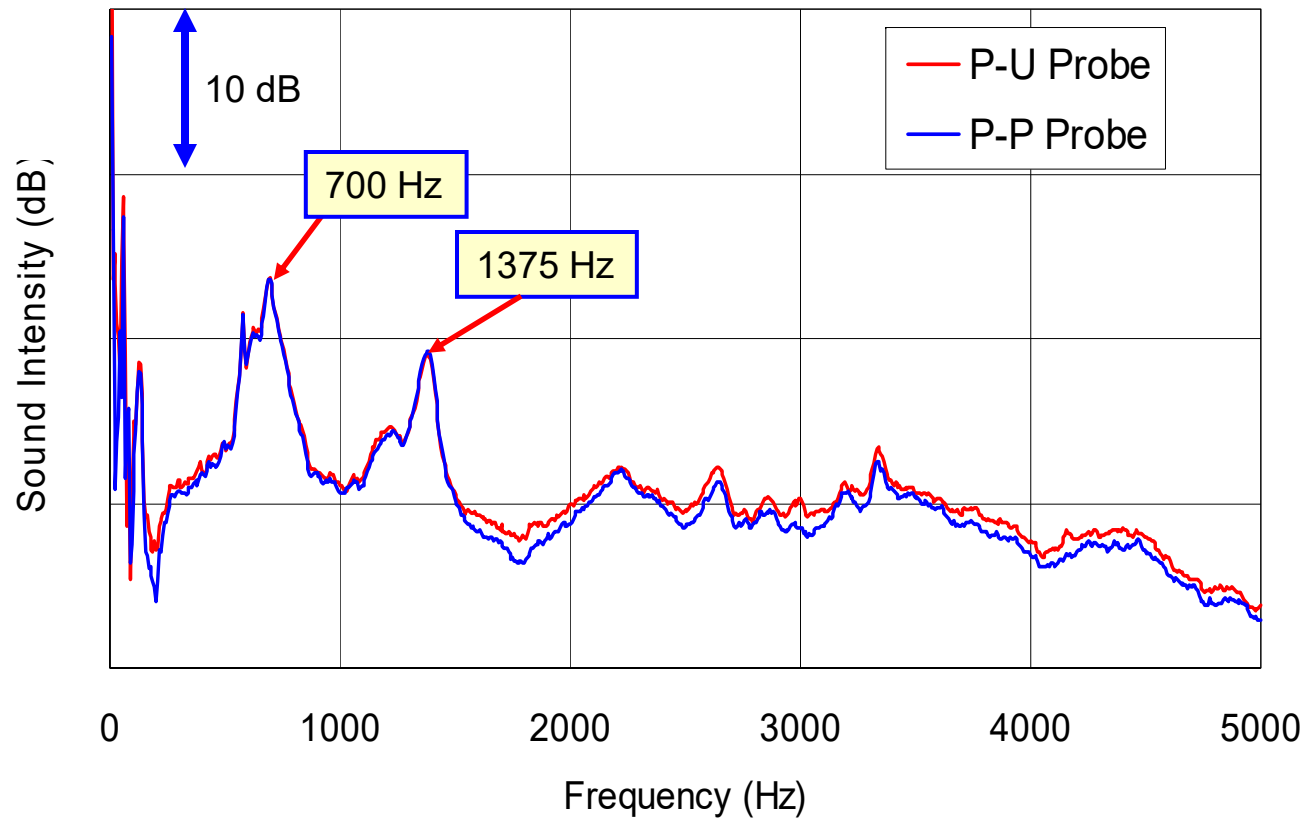


# Motorcycle Engine Transmission

36 Grid Locations

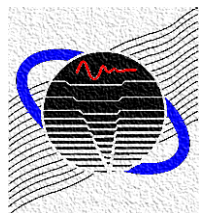
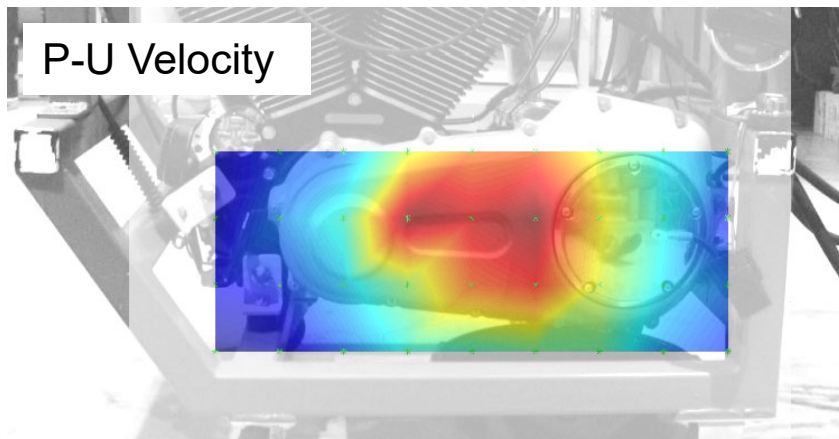
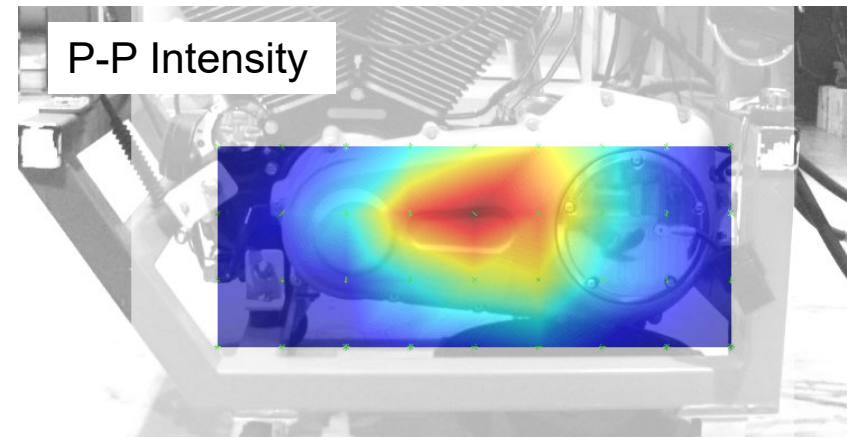
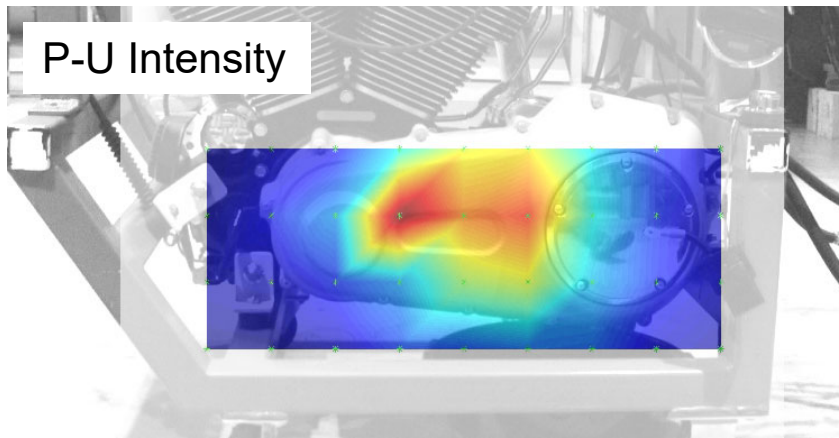


# Averaged Sound Intensity Comparison



# Intensity and Velocity Mapping (700 Hz)

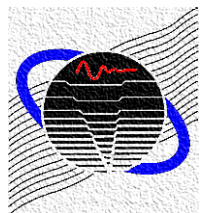
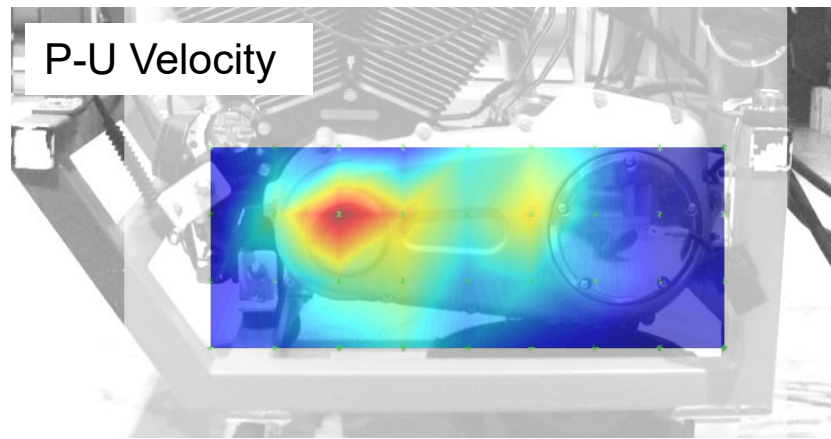
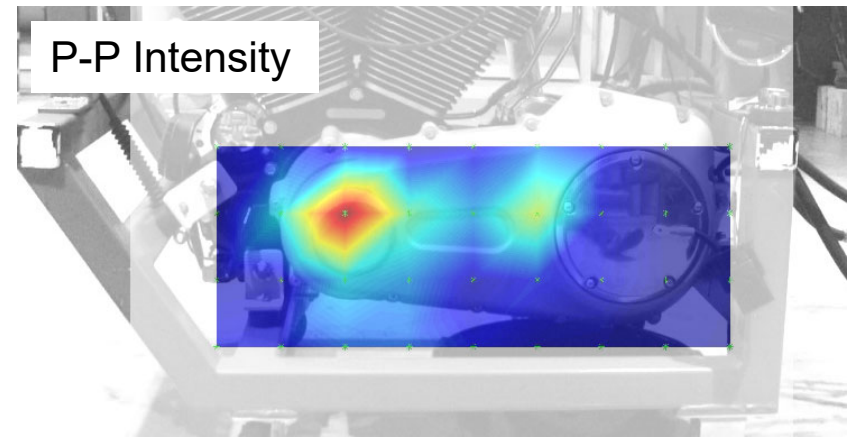
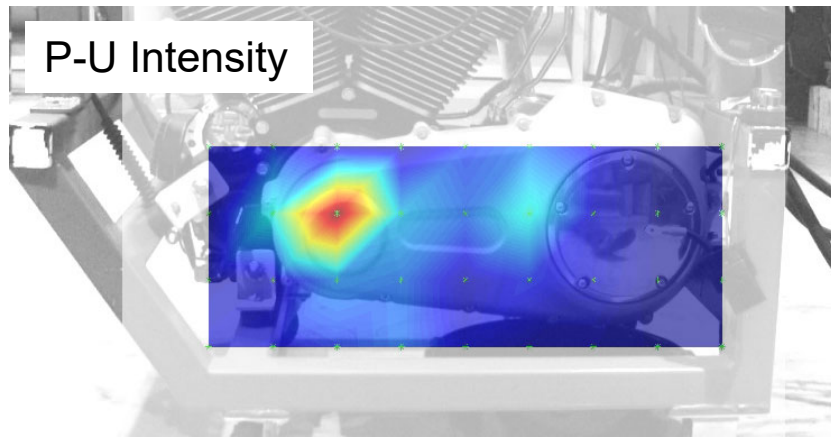
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# Intensity and Velocity Mapping (1375 Hz)

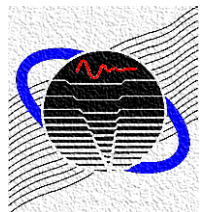
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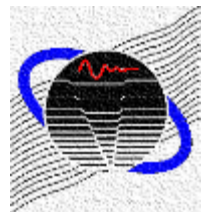


# UAV Measured by P-U Probe

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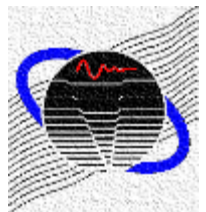
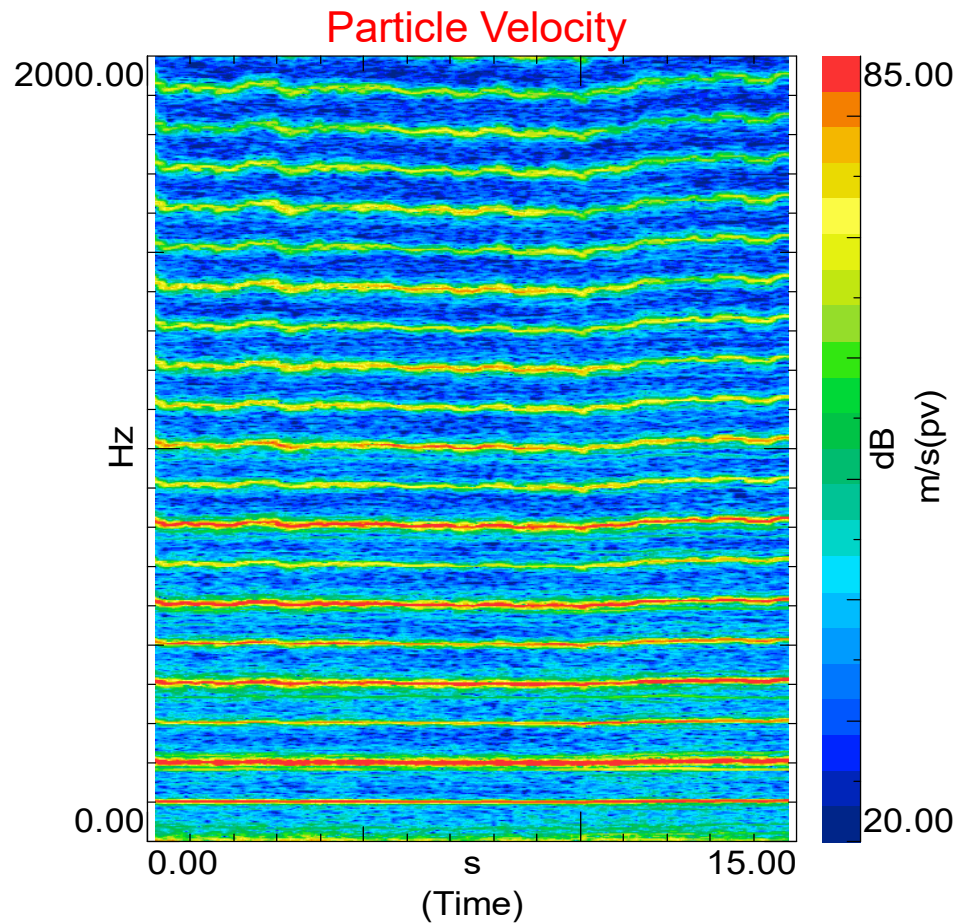
UAV on hovering: with blade ~5700 RPM



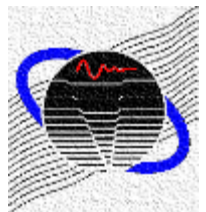
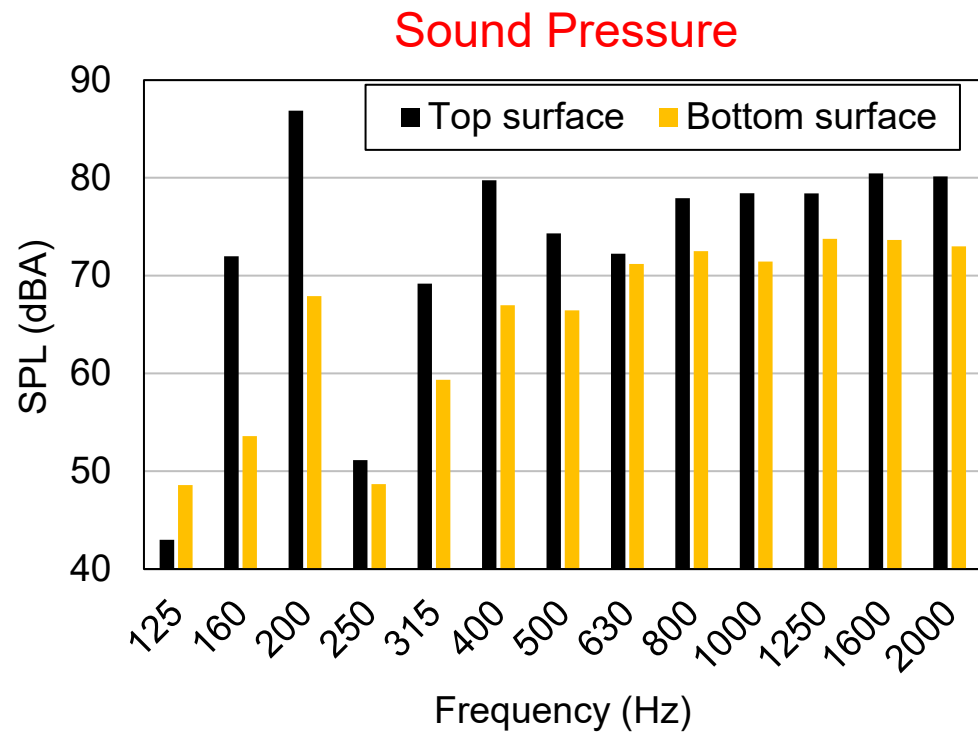
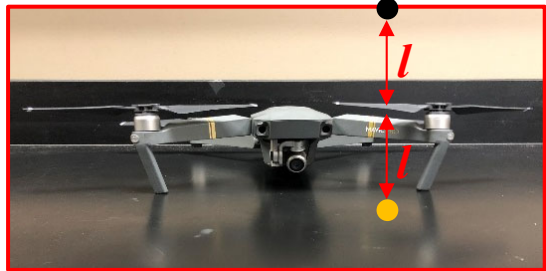


# UAV Measured by P-U Probe

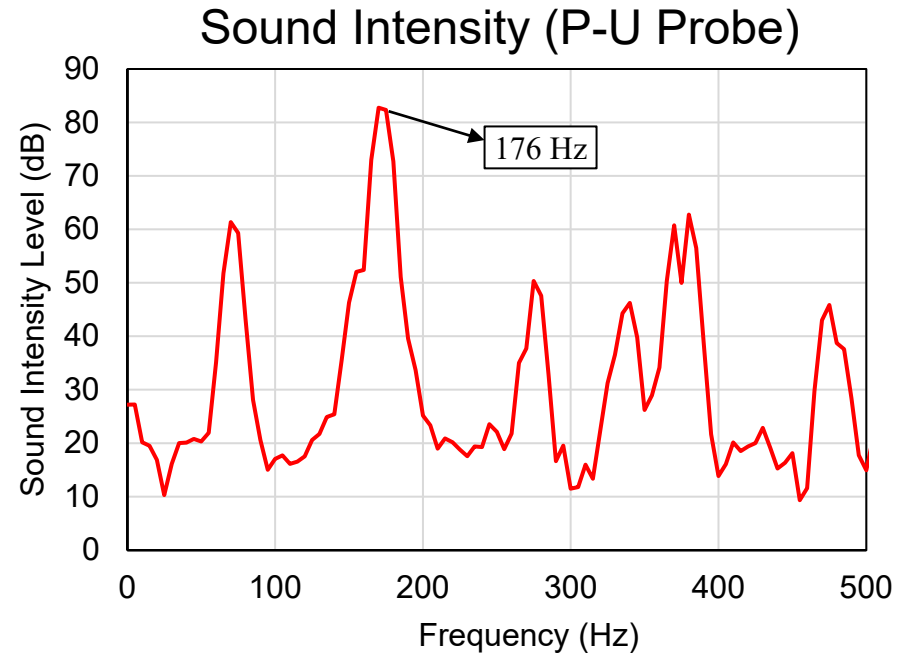
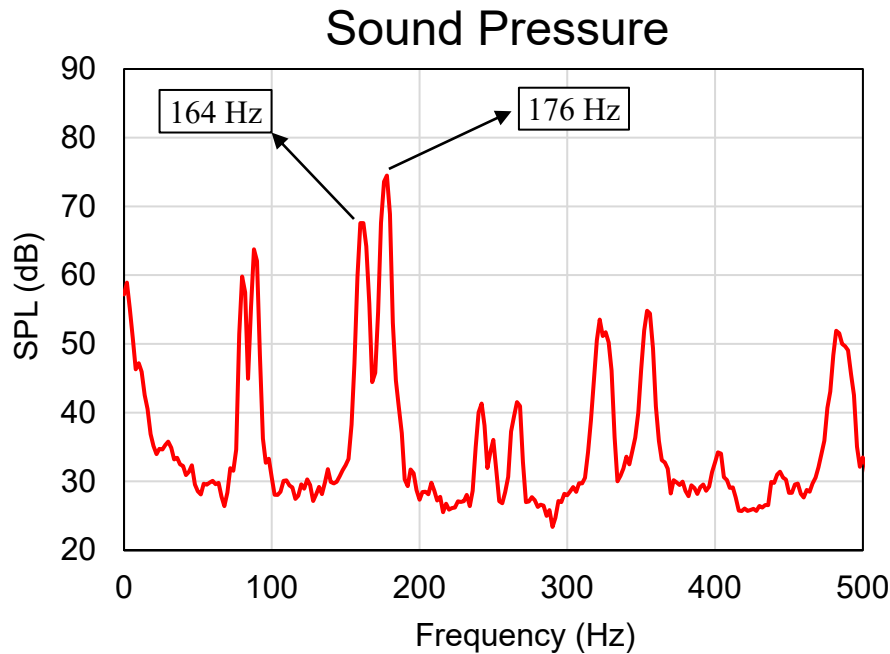
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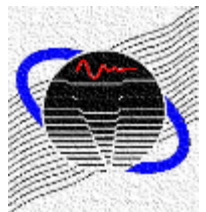
# Sound Pressure Levels



# Near Field Measurement

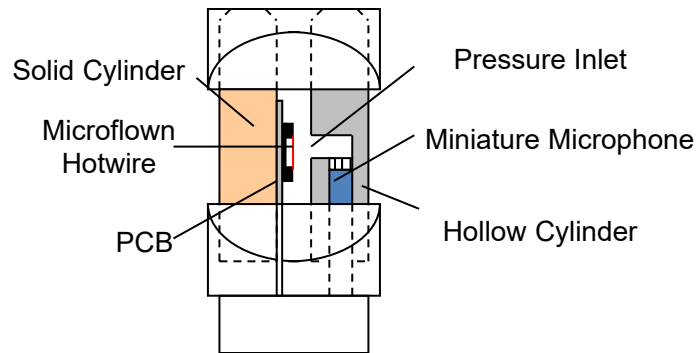


Unlike microphone, P-U probe is able to filter out nearby source components.

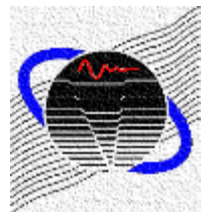
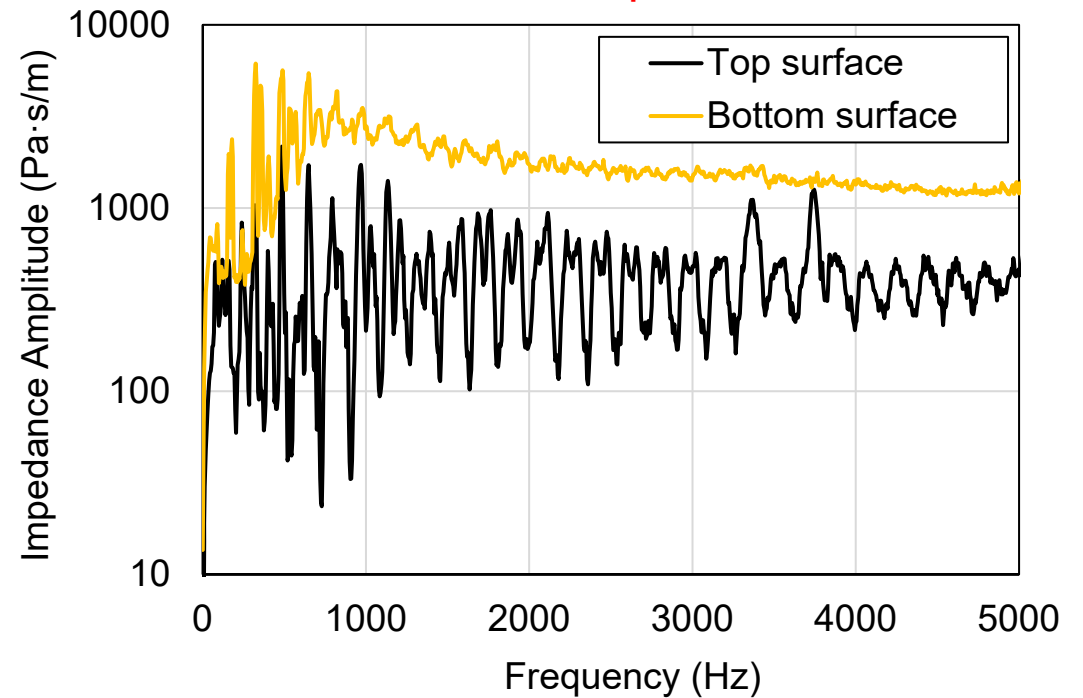


# Top and Bottom Impedance

P-U Probe



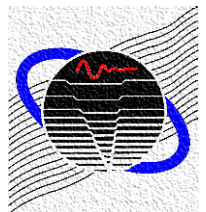
Acoustic Impedance



# Overview

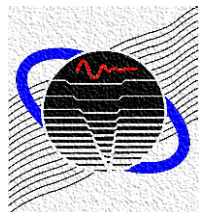
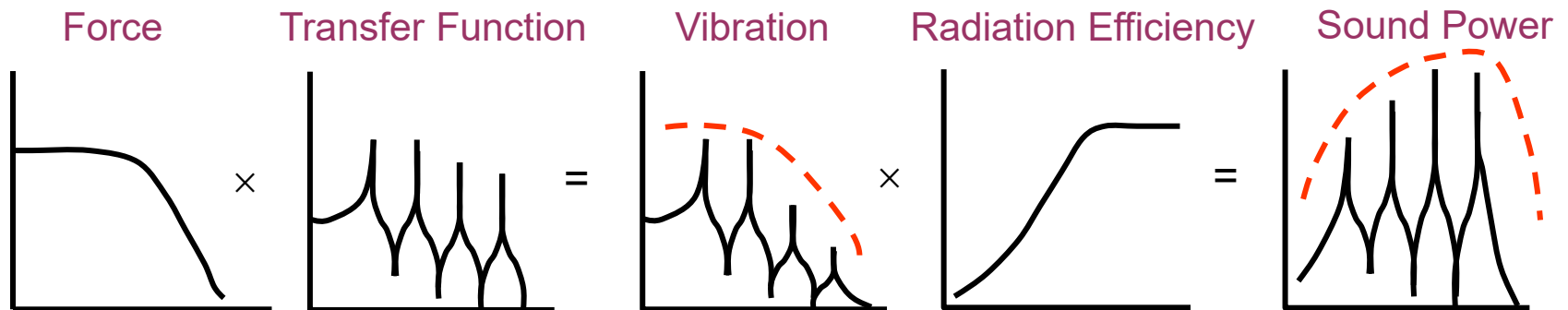
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- [PU Probe](#) UAV Application
- [PU Probe](#) Radiation Efficiency
- [Future Directions](#)



# Radiation Efficiency

## Radiation Efficiency



# Radiation Efficiency

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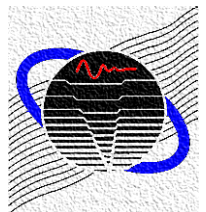
## Radiation Efficiency

$$\sigma_{rad} = \frac{W(f)}{\rho c S \bar{u}^2(f)}$$

$W(f)$  sound power emitted by the vibrating surface

$S$  vibrating surface area

$\bar{u}^2(f)$  spatially averaged RMS value of velocity



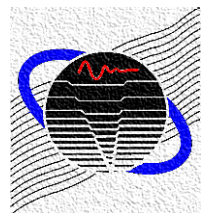
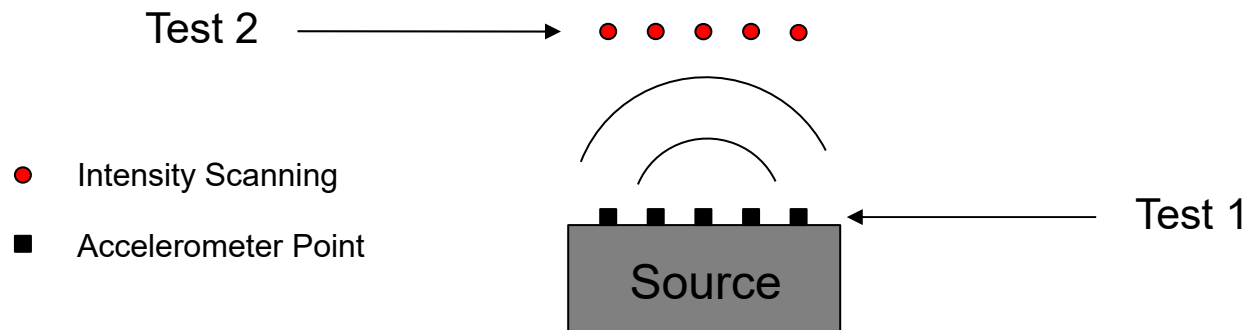


# ISO 7849 Measure Radiation Efficiency

## Radiation Efficiency

ISO-7849 – Determination of airborne sound power levels emitted by machinery using vibration measurement -- Part 2: Engineering method including determination of the adequate radiation factor

- Test 1 – Accelerometer Array for Surface Velocity
- Test 2 – Intensity Scan for Radiated Sound Power

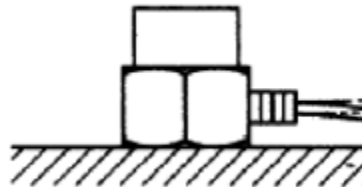


# ISO 7849 Measure Radiation Efficiency

## Radiation Efficiency

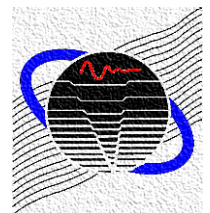
### Disadvantages

- Accelerometers affect surface vibration.
- Requires two separate tests – longer setup time.
- Complicated structures may be difficult to instrument.



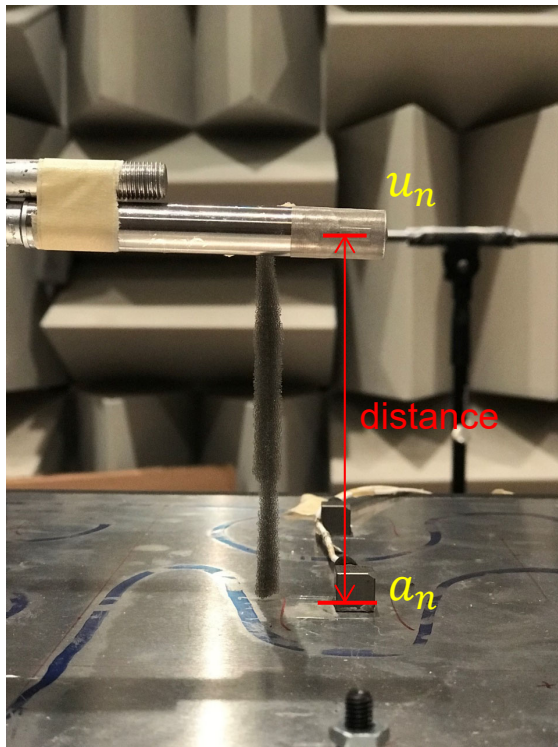
### Alternative – PU Probe

- Both particle velocity and sound power can be measured with same sensor using scanning approaches.



# Surface Velocity Correction

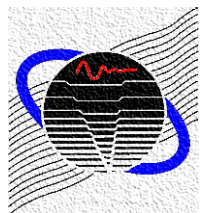
## Radiation Efficiency



Calibration Constant ( $C_{cal}$ )

$$C_{cal} = \frac{u_n^2}{\left(a_n / j\omega\right)^2}$$

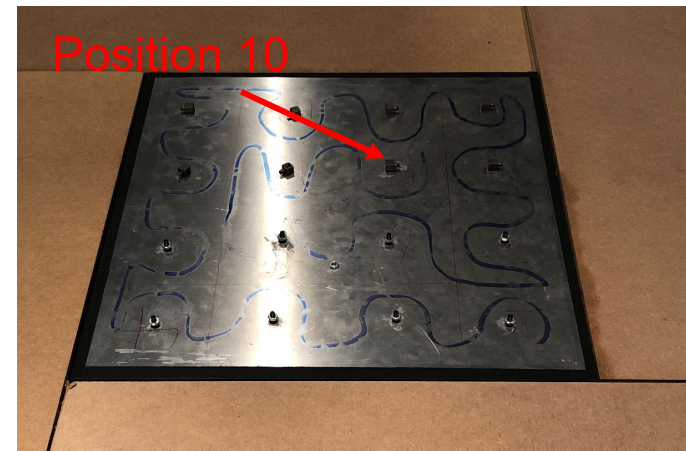
Acceleration ( $a_n$ ) is sampled at a single location. Particle velocity ( $u_n$ ) may be sampled at a single location or multiple locations.



# Aluminum Panel Test Setup

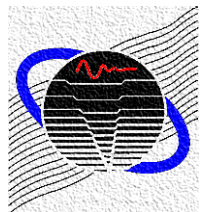
## Radiation Efficiency

- The panel is divided into 16 patches and the standard method was used as a reference.
- Total sound power was measured by PU probe.
- Panel driven by shaker with white noise



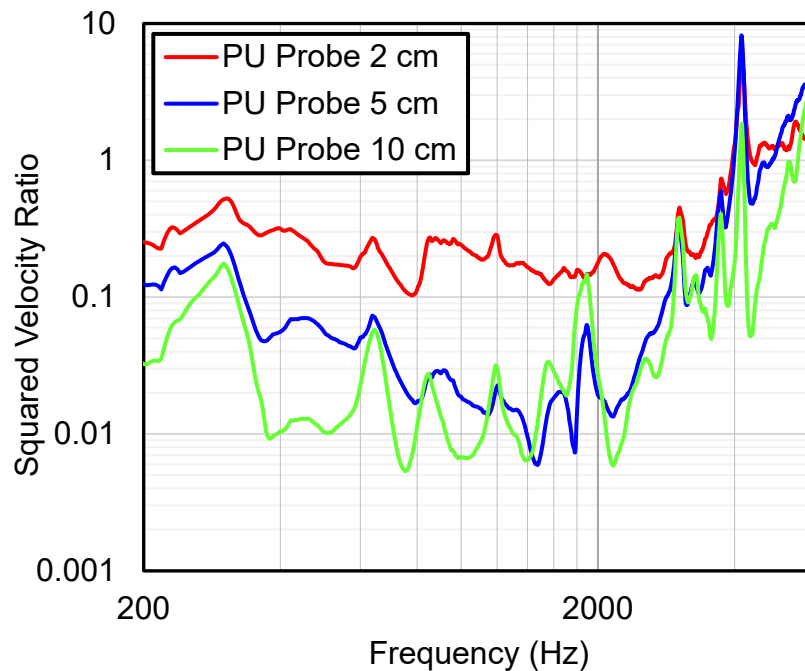
Size:  $0.5 \times 0.5 \text{ m}^2$

Thickness: 3 mm



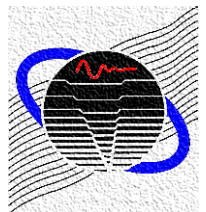
# Aluminum Panel Velocity Ratio

Radiation Efficiency



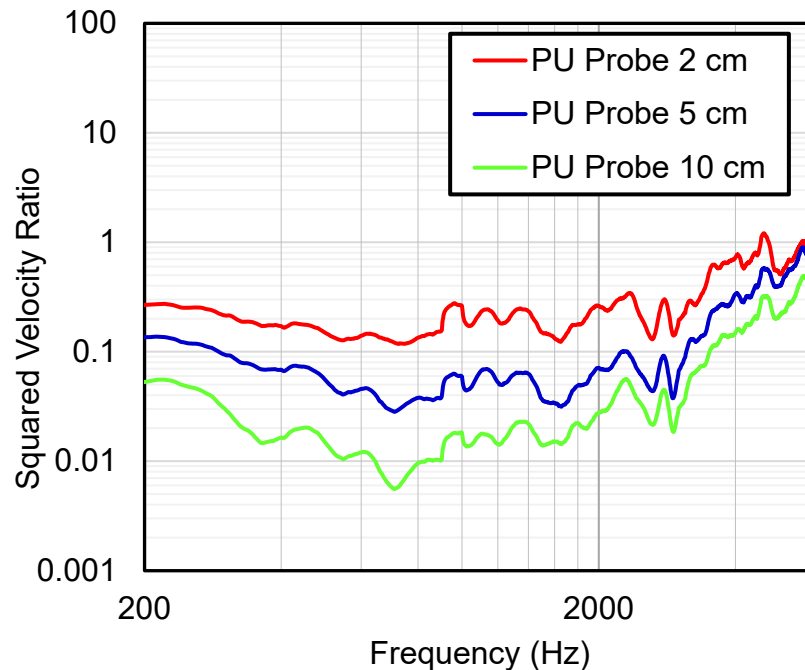
100 Hz running average applied to clean up data.

Single position correction  
Reference: Position 10



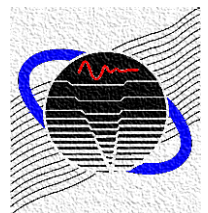
# Aluminum Panel Velocity Ratio

## Radiation Efficiency



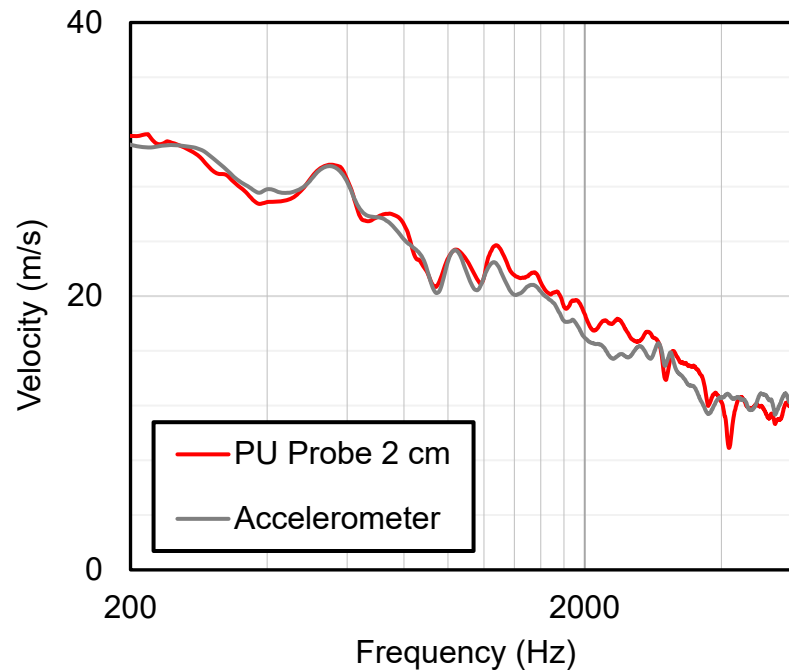
- 100 Hz running average applied to clean up data.
- Calibrated at 16 discrete positions.

Note: Data is shown for illustration purposes but not used for radiation efficiency calculation.

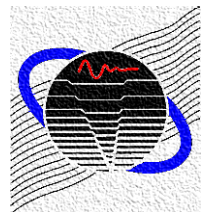


# Aluminum Panel Velocity

Radiation Efficiency



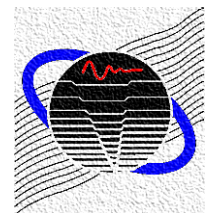
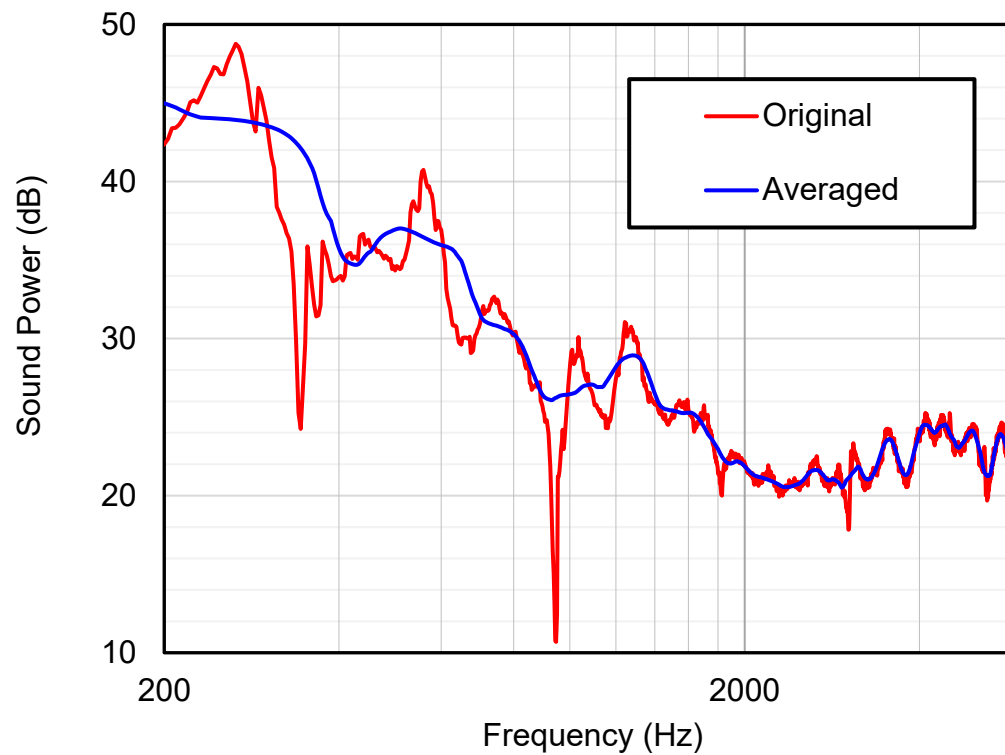
Single position correction  
Reference: Position 10





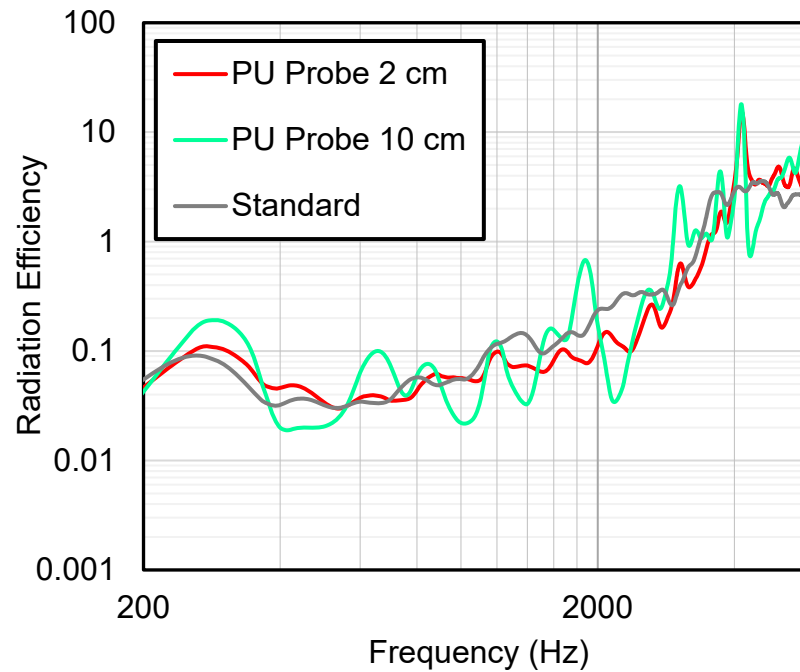
# Aluminum Panel Sound Power

Radiation Efficiency

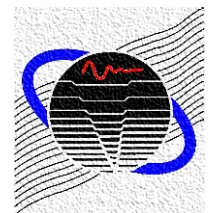


# Aluminum Panel Radiation Efficiency

## Radiation Efficiency



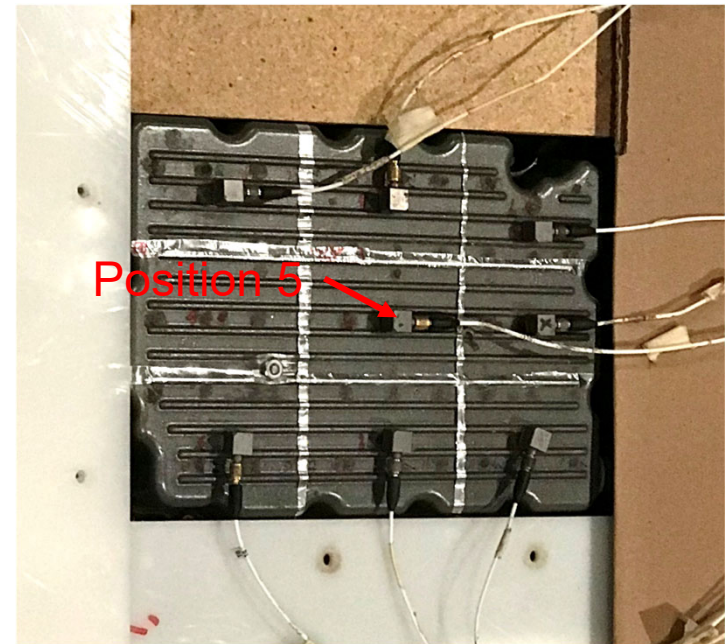
Single position correction  
Reference: Position 10



# Oil Pan Test Setup

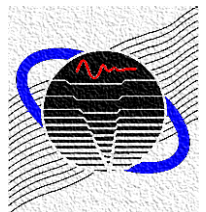
## Radiation Efficiency

- The oil pan is divided into 9 patches and the standard method was used as a reference.
- Total sound power was measured by PU probe.
- Oil pan driven by shaker with white noise.



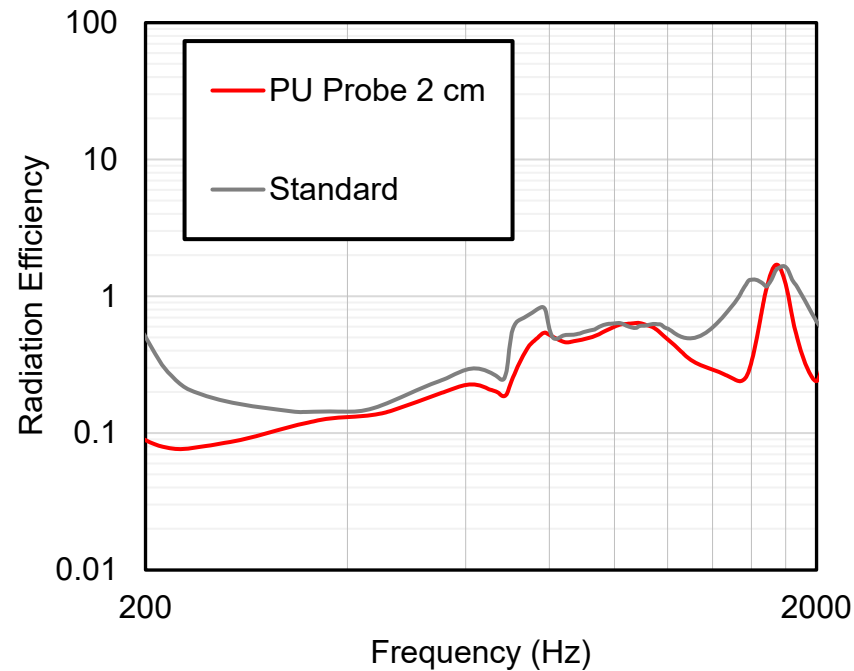
Material: Aluminum

Size:  $0.24 \times 0.17 \text{ m}^2$

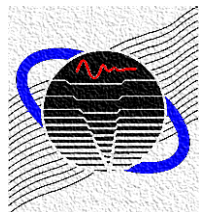


# Oil Pan Radiation Efficiency

## Radiation Efficiency



Single position correction  
Reference: Position 5

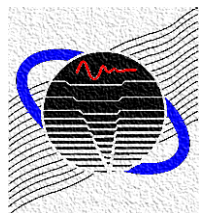


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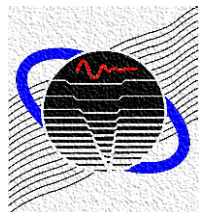


# Future Directions

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## Radiation Efficiency

- UK will continue to investigate new measurement tools using smartphones.
- The PU probe may also be used for sound quality. The particle velocity can be converted to a .wav file and listened to.
- The PU probe may also be used for transient particle velocity measurements. This should have application to pass-by noise.



# References

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## Radiation Efficiency

### Smart Phone Microphones

- L. L. Beranek and T. J. Mellow, *Acoustics: Sound Fields and Transducers*, Academic Press (2012).
- D. A. Bies, C. H. Hansen, and C. Q. Howard, *Engineering Noise Control*, 5th Edition, CRC Press, Boca Raton, FL (2018).

### PU Probe

- H-E de Bree, P. Leussink, T. Korthorst, H. Jansen, T.S. Lammerink, and M. Elwenspoek, "The  $\mu$ -Flown: a Novel Device for Measuring Acoustic Flows", *Sensors and Actuators A: Physical*, 54(1-3), 552-557 (1996).
- H-E de Bree, "The Microflown, a New Particle Velocity Sensor," *Sound and Vibration Magazine*, 39(2), 8, (2005).
- The Microflown E-book, Online, 2009.

### Standard Measurement Procedure for Radiation Efficiency

- ISO/TS 7849-2, *Acoustics — Determination of airborne sound power levels emitted by machinery using vibration measurement — Part 2: Engineering method including determination of the adequate radiation factor*, International Organization for Standardization, Geneva, (2009).

### Radiation Efficiency Research at UK

- S. C. Campbell, D. W. Herrin, B. Birschbach, and P. Crowley, "Measurement of Radiation Efficiency with a Combination Sound Pressure – Particle Velocity Sensor," *Noise-Con 2019*, San Diego, CA, August 26-28 (2019).
- S. C. Campbell, D. W. Herrin, B. Birschbach, and P. Crowley, *Notes on Measurement of Radiation Efficiency*, *Inter-Noise 2018*, August 26-29, Chicago, IL (2018).

